

# **Meta Data API**

# Instruction

Date	2023/06/21
Author	Immanuel
Verified	Arun
Revision	1



# **Table of Contents**

1.	Met	a Data API3
2.	Asse	et Management4
2	2.1.	Create [POST]5
2	2.2.	Read [GET]5
2	2.3.	Update [PUT]6
2	2.4.	Delete [DELETE]6
3.	Conj	figuration7
3	8.1.	GET Bearing Info7
3	8.2.	GET Mount Info7
3	3.3.	GET Equipment Types7
3	8.4.	GET Component Types7
3	8.5.	Equipment Configuration8
3	8.6.	Component Configuration12
4.	Sens	or Assignment
4	.1.	Create24
4	.2.	Read24
4	.3.	Update24
4	.4.	Delete24
5.	Met	ering25
6.	Autl	hentication
7.	Оре	nAPI yml file26



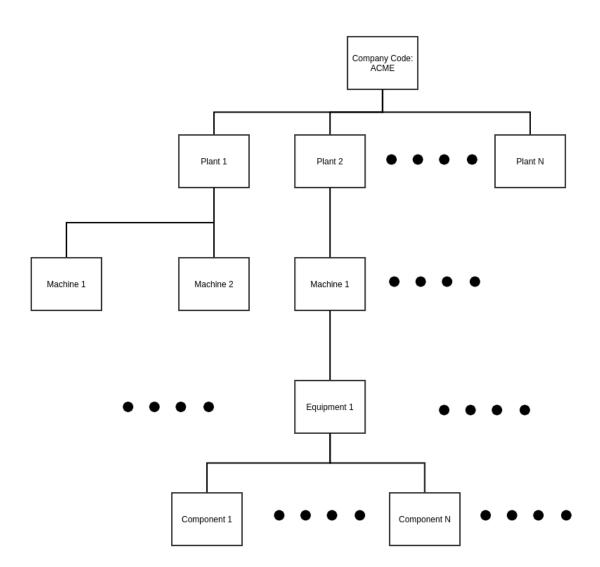
## 1. Meta Data API

- Asset Management
  - o <u>Create [POST]</u>
  - o <u>Read [GET]</u>
  - o Update [PUT]
  - o Delete [DELETE]
- <u>Configuration</u>
  - o <u>GET Bearing Info</u>
  - o <u>GET Mount Info</u>
  - o <u>GET Equipment Types</u>
  - o <u>GET Component Types</u>
  - Equipment Configuration
  - o <u>Component Configuration</u>
- Sensor Assignment
  - o <u>Create</u>
  - o <u>Read</u>
  - o <u>Update</u>
  - o <u>Delete</u>
- <u>Metering</u>
- <u>Authentication</u>
- OpenAPI Yml file



### 2. Asset Management

There are 4 levels of assets creating a tree of the same heights. See the example below



The asset management focuses on maintaining the proper and correct structure of this tree based on the changing realities on the site using CRUD operations.



# 2.1. Create [POST]

```
/assetmanagement/plant
payload={
  "companyId": "DEMO",
  "customName": "Demo Plant",
  "externalId": "1ccc"
}
/assetmanagement/machine
payload={
  "customName": "AUTO-013",
  "plantId": 10000000001,
  "externalId": "121abc"
}
/assetmanagement/equipment
payload={
  "customName": "AUTO-013",
  "equipmentType": "motor",
  "machineId": 20000000001,
  "externalId": "121aaa"
}
/assetmanagement/component
payload={
  "componentType": "motor",
  "componentSubType": "ac",
  "customName": "Sensor #3",
  "equipmentId": 30000000001,
  "externalId": "121aaa"
}
2.2. Read [GET]
```

#### To read current asset information

```
/assetmanagement/plant/info/{plantId}
/assetmanagement/machine/info/{machineId}
/assetmanagement/equipment/info/{equipmentId}
/assetmanagement/component/info/{componentId}
/assetmanagement/tagId/info/{tagId}
```

#### To read the information about children of an asset

```
/assetmanagement/company/{id}/list
/assetmanagement/plant/{id}/list
/assetmanagement/machine/{id}/list
/assetmanagement/equipment/{id}/list
```



# 2.3. Update [PUT]

```
/assetmanagement/plant/{id}
payload={
  "customName": "Demo Plant",
  "externalId": "1ccc"
}
/assetmanagement/machine/{id}
payload={
 "customName": "AUTO-013",
  "externalId": "121abc"
}
/assetmanagement/equipment/{id}
payload={
  "customName": "AUTO-013",
  "externalId": "121aaa"
}
/assetmanagement/component/{id}
payload={
  "customName": "Sensor #3",
  "externalId": "121aaa"
}
```

### 2.4. Delete [DELETE]

```
/assetmanagement/plant/{id}
Delete the plant details from the DB
/assetmanagement/machine/{id}
Delete the machine details from the DB
/assetmanagement/equipment/{id}
```

```
Delete the equipment details from the DB
```

```
/assetmanagement/component/{id}
```



# 3. Configuration

Configuration is done on two levels, equipment and component.

### 3.1. GET Bearing Info

In order to do the component configuration, a call can be made to this endpoint to get all the possible bearing numbers and make

```
/configmanagement/bearing/list [GET]
```

## 3.2. GET Mount Info

A call to this endpoint will return the IDs for each mount type that can be used for sensor assignment

```
/configmanagement/mounttype/{id} [GET]
/configmanagement/mounttype/list [GET]
```

### **3.3. GET Equipment Types**

```
/configmanagement/equipmentType/info [GET]
```

#### **3.4. GET Component Types**

```
/configmanagement/componentType/info [GET]
```



# **3.5. Equipment Configuration**

Configuration	n - in equipment levelA	1	
equipment type	RPM info	response bases on RPM info	component types to select for component config (linked to sheet 2)
	Is the equipment running at constant speed (rpm variation < 5%)?	if yes, block the rest RPM info questions	Pump
		if no, rpm ratio config is not required	Motor
Pump	Is any magnet installed on the shaft of this equipment to measure the RPM?	if yes, after the customer submitted config for each component of this equipment, send a message to remind the customer "if all components added, please configure rpm ratios" and provide a link	Turbine
	RPM ratio	select the master sensor (that measures the RPM) from the component list	Gearbox
	configuration	RPM ratio of this sensor (component) to the master sensor	Other
	Is the equipment running at constant speed (rpm variation < 5%)?	ning at constantif yes, block the rest RPM infoed (rpm variationquestions	
		if no, rpm ratio config is not required	Motor
Compressor	Is any magnet installed on the shaft of this equipment to measure the RPM?	if yes, after the customer submitted config for each component of this equipment, send a message to remind the customer "if all components added, please configure rpm ratios" and provide a link	Turbine
	RPM ratio configuration	select the master sensor (that measures the RPM) from the component list	Gearbox



		RPM ratio of this sensor (component) to the master sensor	Other
	Is the equipment running at constant speed (rpm variation < 5%)?	if yes, block the rest RPM info questions	Fan
		if no, rpm ratio config is not required	Motor
Fan	Is any magnet installed on the shaft of this equipment to measure the RPM?	if yes, after the customer submitted config for each component of this equipment, send a message to remind the customer "if all components added, please configure rpm ratios" and provide a link	Turbine
	RPM ratio	select the master sensor (that measures the RPM) from the component list	Gearbox
	configuration	RPM ratio of this sensor (component) to the master sensor	Other
	Is the equipment running at constant speed (rpm variation < 5%)?	if yes, block the rest RPM info questions	Blower
		if no, rpm ratio config is not required	Motor
Blower	Is any magnet installed on the shaft of this equipment to measure the RPM?	if yes, after the customer submitted config for each component of this equipment, send a message to remind the customer "if all components added, please configure rpm ratios" and provide a link	Turbine
	RPM ratio	select the master sensor (that measures the RPM) from the component list	Gearbox
	configuration	RPM ratio of this sensor (component) to the master sensor	Other
Transformer	no need to ask RPM questions	NA	Transformer



	Is this a rotating equipment	if no, block the rest RPM info questions	if not rotating equipment, only Other; otherwise, all the components bel
	Is the equipment running at constant speed (rpm variation < 5%)?	if yes, block the rest RPM info questions	Motor
		if no, rpm ratio config is not required	Turbine
Other	Is any magnet installed on the shaft of this equipment to measure the RPM?	if yes, after the customer submitted config for each component of this equipment, send a message to remind the customer "if all components added, please configure rpm ratios" and provide a link	Gearbox
	RPM ratio configuration (after	select the master sensor (that measures the RPM) from the component list	Pump
	component config)	RPM ratio of this sensor (component) to the master sensor	Compressor
			Fan
			Blower
			Other

The table above is just to help the understanding of how the object below is formatted. It should be noted that only one key under config is allowed, this means that equipment can be configured for one type.



Note: If isConstantSpeed is True, We can't set isMagnetInstalled to True

```
/configmanagement/equipment [POST]
{
    "config": {
        "pump": {
            "isRotatingEquipment": true,
            "isConstantSpeed": false,
            "isMagnetInstalled": true
        },
        "compressor": {
            "isRotatingEquipment": true,
            "isConstantSpeed": false,
            "isMagnetInstalled": true
       },
"fan": {
";sR
            "isRotatingEquipment": true,
            "isConstantSpeed": false,
            "isMagnetInstalled": true
        },
        "blower": {
            "isRotatingEquipment": true,
            "isConstantSpeed": false,
            "isMagnetInstalled": true
        },
        "transformer": {
            "isRotatingEquipment": true,
            "isConstantSpeed": false,
            "isMagnetInstalled": true
        },
        "other": {
            "isRotatingEquipment": true,
            "isConstantSpeed": false,
            "isMagnetInstalled": true
        }
    },
    "equipmentId": 9762,
    "companyId": "ACME",
    "description": "Test"
}
```



# **3.6. Component Configuration**

component type	component sub-type	info required for condifuration	Fault mode configuration	
		constant speed (rpm variation < 5%) or not (take the answer from the equipment questionaire if available)		
		RPM (constant speed) or Min&Max RPM (variable speed)	if RPM=0, don't configure any fault mode	
		Bearing type (journal bearing or anti-friction bearing)	if it is journal bearing, configure journal bearing faults (find in sheet 3); otherwise configure unbalance, misalignment, l	
	AC Motor	bearing number (bearing make and bearing number if it is anti-friction bearing)	if bearing number is given, configure bearing_faults	
		allowing the user to add more bearings (if anti- friction bearing)multiple bearings to be enbaled	if both eletrical line frequency and number of rotor bars are given, configure induction_motor_stator_rotor on < 5%) or not (take the answer	
		eletrical line frequency		
Motor		number of rotor bars		
		constant speed (rpm variation < 5%) or not (take the answer from the equipment questionaire if available)		
		RPM (constant speed) or Min&Max RPM (variable speed)	if RPM=0, don't configure any fault mode	
	DC Motor	Bearing type (journal bearing or anti-friction bearing)	if it is journal bearing, configure journal bearing faults (find in sheet 3); otherwise configure unbalance, misalignment, 1	
		bearing number (bearing make and bearing number if it is anti-friction bearing)	if bearing number is given, configure bearing_faults	
		allowing the user to add more bearings (if anti- friction bearing)		



		constant speed (rpm variation < 5%) or not (take the answer from the equipment questionaire if available)	
		RPM (constant speed) or Min&Max RPM (variable speed)	if RPM=0, don't configure any fault mode
0	other	Bearing type (journal bearing or anti-friction bearing)	if it is journal bearing, configure journal bearing faults; otherwise configure unbalance, misalignment, looseness
		bearing number (bearing make and bearing number if it is anti-friction bearing)	if bearing number is given, configure bearing_faults
		allowing the user to add more bearings (if anti- friction bearing)	
		constant speed (rpm variation < 5%) or not (take the answer from the equipment questionaire if available)	
		RPM (constant speed) or Min&Max RPM (variable speed)	if RPM=0, don't configure any fault mode
	Steam turbine	Bearing type (journal bearing or anti-friction bearing)	if it is journal bearing, configure journal bearing faults (find in sheet 3); otherwise configure unbalance, misalignment, 1
Turbine		bearing number (bearing make and bearing number if it is anti-friction bearing)	if bearing number is given, configure bearing_faults
		allowing the user to add more bearings (if anti- friction bearing)	allowing the user to add more bearings (if anti-friction bearing)
		constant speed (rpm variation from the equipment questiona	< 5%) or not (take the answer aire if available)
	Gas turbine	RPM (constant speed) or Min&Max RPM (variable speed)	if RPM=0, don't configure any fault mode



		Bearing type (journal bearing or anti-friction bearing)	<i>if it is journal bearing, configure journal bearing faults (find in sheet 3); otherwise configure unbalance, misalignment, l</i>
		bearing number (bearing make and bearing number if it is anti-friction bearing)	if bearing number is given, configure bearing_faults
		allowing the user to add more bearings (if anti- friction bearing)	allowing the user to add more bearings (if anti-friction bearing)
		constant speed (rpm variation from the equipment questiona	n < 5%) or not (take the answer iire if available)
		RPM (constant speed) or Min&Max RPM (variable speed)	<i>if RPM=0, don't configure any</i> <i>fault mode</i> if it is journal bearing, configure journal bearing faults (find in sheet 3); otherwise configure unbalance, misalignment, 1
	other	Bearing type (journal bearing or anti-friction bearing)	journal bearing faults (find in sheet 3); otherwise configure
		bearing number (bearing make and bearing number if it is anti-friction bearing)	if bearing number is given, configure bearing_faults
		allowing the user to add more bearings (if anti- friction bearing)	allowing the user to add more bearings (if anti-friction bearing)
		constant speed (rpm variation from the equipment questiona	< 5%) or not (take the answer aire if available)
		RPM (constant speed) or Min&Max RPM (variable speed)	if RPM is provided, configure unbalance, misalignment, looseness
Gearbox	Fixed-axis gearbox	each shaft: RPM_in, number of teenth T1, T2, RPM_out(automatically calculated based on RPM_in, T1,T2)	configure gear_fault
		each shaft: bearing number (bearing make and bearing number)	if bearing number is given, configure bearing_faults



		allowing the user to add more shafts and configure accordingly - multiple GMFs to be enabled	
		constant speed (rpm variation from the equipment questiona	< 5%) or not (take the answer aire if available)
		RPM (constant speed) or Min&Max RPM (variable speed)	<ul> <li>if RPM=0, don't configure any fault mode</li> <li>if it is journal bearing, configure journal bearing faults (find in sheet 3); otherwise configure unbalance, misalignment, l</li> </ul>
	Centrifugal Pump	Bearing type (journal bearing or anti-friction bearing)	
		bearing number (bearing make and bearing number if it is anti-friction bearing)	if bearing number is given, configure bearing_faults
		allowing the user to add more bearings (if anti- friction bearing)	
		number of vanes	configure pump_vane_fault
Pump	Sucker Rod Pump (stuffing bo	no need	configure polish_rod_misalignment_ae under aeFaultDetection
		constant speed (rpm variation < 5%) or not (take the answer from the equipment questionaire if available)	
		RPM (constant speed) or Min&Max RPM (variable speed)	if RPM=0, don't configure any fault mode
	other	Bearing type (journal bearing or anti-friction bearing)	if it is journal bearing, configure journal bearing faults (find in sheet 3); otherwise configure unbalance, misalignment, 1
		bearing number (bearing make and bearing number if it is anti-friction bearing)	if bearing number is given, configure bearing_faults
		allowing the user to add more bearings (if anti- friction bearing)	allowing the user to add more bearings (if anti-friction bearing)



	number of vanes (if applicable)	configure pump_vane_fault	
	constant speed (rpm variation < 5%) or not (take the answer from the equipment questionaire if available)		
	RPM (constant speed) or Min&Max RPM (variable speed)	if RPM=0, don't configure any fault mode	
Centrifugal Fan	Bearing type (journal bearing or anti-friction bearing)	if it is journal bearing, configure journal bearing faults; otherwise configure unbalance, misalignment, looseness	
	bearing number (bearing make and bearing number if it is anti-friction bearing)	if bearing number is given, configure bearing_faults	
	allowing the user to add more bearings (if anti- friction bearing)		
	number of blades	configure pump_vane_fault	
	constant speed (rpm variation < 5%) or not (take the answer from the equipment questionaire if available)		
	Min&Max RPM (variable speed)fault modeBearing type (journal bearing or anti-friction bearing)if it is journal bear journal bearing fau sheet 3); otherwise	if RPM=0, don't configure any fault mode	
other		if it is journal bearing, configure journal bearing faults (find in sheet 3); otherwise configure unbalance, misalignment, 1	
b n it a n fi n	bearing number (bearing make and bearing number if it is anti-friction bearing)	if bearing number is given, configure bearing_faults	
	allowing the user to add more bearings (if anti- friction bearing)	allowing the user to add more bearings (if anti-friction bearing)	
	number of blades (if applicable)	configure pump_vane_fault	
Centrifugal Blower	constant speed (rpm variation from the equipment questiona	< 5%) or not (take the answer aire if available)	
	Fan other Centrifugal	applicable)Centrifugalconstant speed (rpm variation from the equipment questional RPM (constant speed) or Min&Max RPM (variable speed)Bearing type (journal bearing or anti-friction bearing)Bearing number (bearing make and bearing number if it is anti-friction bearing)allowing the user to add more bearings (if anti- friction bearing)number of bladesconstant speed (rpm variation from the equipment questional Bearing type (journal bearing)allowing the user to add more bearings (if anti- friction bearing)number of bladesconstant speed (rpm variation from the equipment questional Bearing type (journal bearing or anti-friction bearing)otherbearing number (bearing make and bearing number if it is anti-friction bearing)allowing the user to add more bearings (if anti- friction bearing)allowing the user to add more bearings (if anti- friction bearing)allowing the user to add more bearings (if anti- friction bearing)number of blades (if applicable)Centrifugalconstant speed (rpm variation	



		RPM (constant speed) or Min&Max RPM (variable speed)	if RPM=0, don't configure any fault mode
		Bearing type (journal bearing or anti-friction bearing)	if it is journal bearing, configure journal bearing faults (find in sheet 3); otherwise configure unbalance, misalignment, 1
		bearing number (bearing make and bearing number if it is anti-friction bearing)	if bearing number is given, configure bearing_faults
		allowing the user to add more bearings (if anti- friction bearing)	
		number of blades	configure pump_vane_fault
		constant speed (rpm variation from the equipment questiona	< 5%) or not (take the answer nire if available)
		RPM (constant speed) or Min&Max RPM (variable speed)	if RPM=0, don't configure any fault mode
	other	Bearing type (journal bearing or anti-friction bearing)	if it is journal bearing, configure journal bearing faults (find in sheet 3); otherwise configure unbalance, misalignment, 1
		bearing number (bearing make and bearing number if it is anti-friction bearing)	if bearing number is given, configure bearing_faults
		allowing the user to add more bearings (if anti- friction bearing)	allowing the user to add more bearings (if anti-friction bearing)
		number of blades (if applicable)	configure pump_vane_fault
		constant speed (rpm variation from the equipment questiona	< 5%) or not (take the answer nire if available)
Compressor	Reciprocating air compressor	RPM (constant speed) or Min&Max RPM (variable speed)	if RPM=0, don't configure any fault mode
		sensor installed on cranke case or cylider	configure fault modes of cranke case or cylinder (find in sheet 3)



		constant speed (rpm variation < 5%) or not (take the answer from the equipment questionaire if available)		
		RPM (constant speed) or Min&Max RPM (variable speed)	if RPM=0, don't configure any fault mode	
	other	Bearing type (journal bearing or anti-friction bearing)	if it is journal bearing, configure journal bearing faults (find in sheet 3); otherwise configure unbalance, misalignment, l	
		bearing number (bearing make and bearing number if it is anti-friction bearing)	if bearing number is given, configure bearing_faults	
		allowing the user to add more bearings (if anti- friction bearing)	allowing the user to add more bearings (if anti-friction bearing)	
Transformer	power transformer	electrical line frequency	configure partial_dischage under aeFaultDetection	
		rotating component or not (take the answer from the equipment questionaire if available)	if not, configure rpm = 0, no fault mode to configure	
		if rotation component, consta not (take the answer from the available)	nt speed (rpm variation < 5%) or equipment questionaire if	
		RPM (constant speed) or Min&Max RPM (variable speed)	if RPM=0, don't configure any fault mode	
Other	other	Bearing type (journal bearing or anti-friction bearing)	if it is journal bearing, configure journal bearing faults (find in sheet 3); otherwise configure unbalance, misalignment, 1	
		bearing number (bearing make and bearing number if it is anti-friction bearing)	if bearing number is given, configure bearing_faultsD92	
	allowing the user to add more bearings (if anti- friction bearing)	more bearings (if anti-	allowing the user to add more bearings (if anti-friction bearing)	



The table above is just to help the understanding of how the object below is formatted. It should be noted that only one key under config is allowed, this means that components can be configured for one type.

```
{
  "config": {
      "motor": {
        "ac": {
          "speed": {
            "minRPM": 200,
            "maxRPM": 400
          },
          "bearing": {
            "bearingType": 0,
            "antiFriction": [
               {
                 "bearingNumber": "1000",
                 "bearingMake": "ISOS"
               }
            ]
          },
          "stator": {
            "eletricalLineFreq": 2.0,
            "numberOfBars": 10
          }
        },
        "dc": {
          "speed": {
            "minRPM": 300,
            "maxRPM": null
          },
          "bearing": {
            "bearingType": 1,
            "antiFriction": [
              {
                "bearingNumber": "2000",
                "bearingMake": "IOSS"
              },
               {
                 "bearingNumber": "2001",
                "bearingMake": "SISS"
              }
            ]
          }
        },
        "other": {
          "speed": {
            "minRPM": 200,
            "maxRPM": 400
          },
          "bearing": {
            "bearingType": 0,
            "antiFriction": [
```

/configmanagement/component [POST]



```
{
          "bearingNumber": "1000",
          "bearingMake": "ISOS"
        }
      ]
    }
  }
},
"turbine": {
  "steam": {
    "speed": {
      "minRPM": 200,
      "maxRPM": 400
    },
    "bearing": {
      "bearingType": 0,
      "antiFriction": [
        {
          "bearingNumber": "1000",
          "bearingMake": "ISOS"
        }
      ]
    }
  },
  "gas": {
    "speed": {
      "minRPM": 300,
      "maxRPM": null
    },
    "bearing": {
      "bearingType": 1,
      "antiFriction": [
        {
          "bearingNumber": "2000",
          "bearingMake": "IOSS"
        },
        {
          "bearingNumber": "2001",
          "bearingMake": "SISS"
        }
      ]
    }
  },
  "other": {
    "speed": {
      "minRPM": 200,
      "maxRPM": 400
    },
    "bearing": {
      "bearingType": 0,
      "antiFriction": [
        {
          "bearingNumber": "1000",
          "bearingMake": "ISOS"
        }
      ]
```



```
}
  }
},
"gearbox": {
  "fixedAxis": [
    {
      "rpmIn": 500,
      "noOfTeeth1": 24,
      "noOfTeeth2": 42,
      "shaftBearingNumber": "1200",
      "shaftBearingMake": "SSIO"
    },
    {
      "rpmIn": 600,
      "noOfTeeth1": 14,
      "noOfTeeth2": 32,
      "shaftBearingNumber": "1201",
      "shaftBearingMake": "SSIS"
    }
  ]
},
"pump": {
  "centrifugal": {
    "speed": {
      "minRPM": 200,
      "maxRPM": 400
    },
    "bearing": {
      "bearingType": 0,
      "antiFriction": [
        {
          "bearingNumber": "1000",
          "bearingMake": "ISOS"
        }
      ]
    },
    "noVanes": "interger or null"
  },
  "suckerRod": {
    "active": 1
  },
  "other": {
    "speed": {
      "minRPM": 200,
      "maxRPM": 400
    },
    "bearing": {
      "bearingType": 0,
      "antiFriction": [
        {
          "bearingNumber": "1000",
          "bearingMake": "ISOS"
        }
      ]
    },
    "noVanes": 3
```



```
}
},
"fan": {
  "centrifugal": {
    "speed": {
      "minRPM": 200,
      "maxRPM": 400
    },
    "bearing": {
      "bearingType": 0,
      "antiFriction": [
        {
          "bearingNumber": "1000",
          "bearingMake": "ISOS"
        }
      ]
    },
    "noBlades": null
  },
  "other": {
    "speed": {
      "minRPM": 300,
      "maxRPM": null
    },
    "bearing": {
      "bearingType": 1,
      "antiFriction": [
        {
          "bearingNumber": "2000",
          "bearingMake": "IOSS"
        },
        {
          "bearingNumber": "2001",
          "bearingMake": "SISS"
        }
      ]
    },
    "noBlades": 4
  }
},
"blower": {
  "centrifugal": {
    "speed": {
      "minRPM": 200,
      "maxRPM": 400
    },
    "bearing": {
      "bearingType": 0,
      "antiFriction": [
        {
          "bearingNumber": "1000",
          "bearingMake": "ISOS"
        }
      ]
    },
    "noBlades": null
```



```
},
    "other": {
      "speed": {
        "minRPM": 300,
        "maxRPM": null
      },
      "bearing": {
        "bearingType": 1,
        "antiFriction": [
          {
            "bearingNumber": "2000",
            "bearingMake": "IOSS"
          },
          {
            "bearingNumber": "2001",
            "bearingMake": "SISS"
          }
        ]
      },
      "noBlades": 3
    }
  },
  "transfomer": {
    "power": {
      "eletricalLineFreq": 4.5
    }
 },
  "other": {
    "speed": {
      "minRPM": 200,
      "maxRPM": 400
    },
    "bearing": {
      "bearingType": 0,
      "antiFriction": [
        {
          "bearingNumber": "1000",
          "bearingMake": "ISOS"
        }
      ]
    }
  }
},
"tagId": "LLLLZQH3R9287MRMDE83383VR2F",
```

}



#### 4. Sensor Assignment

#### 4.1. Create

```
/sensorassignment [POST]
{
    "sensorId": "30000c2a691f4072",
    "tagId": "ACCLMR100893910GBI82105S9RA",
    "companyId": "ACCL",
    "mountTypeId": "5e42a0ea6a4b956e5dda7ed5"
}
```

#### 4.2. Read

```
/sensorassignment/{sensorId} [GET]
/sensorassignment/list/{companyId} [GET]
```

#### 4.3. Update

```
/sensorassignment/{sensorId} [PUT]
```

{
 "mountTypeId": 61f2f4c882e19c6a4987d69d",
}

#### 4.4. Delete

```
/sensorassignment/{sensorId} [DELETE]
```



# 5. Metering

API will be restricted to 1000 calls/day for each account

# 6. Authentication

## Token Generating URL:

```
curl --location
'https://keycloak.nanoprecisedataservices.com/realms/master/protocol/openid-
connect/token' \
--header 'Content-Type: application/x-www-form-urlencoded' \
--data-urlencode 'username=********' \
--data-urlencode 'grant_type=********' \
--data-urlencode 'client_id=*******' \
--data-urlencode 'client_secret=*******'
```

Users need to sign in every 24 hours to get a new token that is valid for the same period.



# 7. OpenAPI yml file

Available under following <u>link</u>